

Table of Contents

Preface	ix
PART 1. THE MARINE ENVIRONMENT	1
Part 1. Introduction	3
Chapter 1. Problematics	5
1.1. History	5
1.2. Underwater acoustics	7
1.2.1. Communications channel	8
1.2.2. Knowledge of the channel	8
1.3. Applications	9
1.3.1. Civil applications	9
1.3.2. Military applications	9
1.4. Comparison with radar	10
1.5. Submarine detection and warfare	11
1.6. Submarine detection	11
1.7. Submarine detection: a veritable challenge	12
1.8. Overcoming the effects of the ocean	13
1.8.1. Acoustics	13
1.8.2. Propagation	14
1.8.3. Unknown noise	16
1.8.4. Unknown signal	16
1.9. Sonar and information processing	16
Chapter 2. Sound Propagation in the Marine Environment	19
2.1. General points	19
2.2. Characteristics of the marine environment	19
2.3. Models used	22
2.4. Propagation phenomena	28
2.4.1. Deep water	28
2.4.2. Reflection	32
2.4.3. Coherence and stability of sound channels	33
2.5. Application examples	33
2.5.1. Simplified equations, range and optimum frequency	33
2.5.2. Use of towed sonar	38
2.5.3. Study of transmission problems	38
2.5.4. Vertical telemetry	38
Chapter 3. Noises and Reverberation	41
3.1. Classification of ambient noises	41
3.2. Analysis of noise sources	45

3.2.1. Hydrodynamic sources	45
3.2.2. Maritime traffic	49
3.2.3. Seismic sources	50
3.2.4. Biological sources	51
3.2.5. Additional sources	51
3.3. Wenz' model of sea noise	51
3.4. Directivity of sea noise	52
3.4.1. Application to antenna production	54
3.5. Reverberation	55
3.5.1. Surface reverberation	56
3.5.2. Volume reverberation	59
3.5.3. Seabed reverberation	62
Chapter 4. Radiated and Inherent Noises	65
4.1. Radiated noise	65
4.1.1. Engine noise	65
4.1.2. Propeller noises	67
4.1.3. Hydrodynamic noise	70
4.1.4. Summary of the sources of radiated noise	71
4.1.5. Directivity	72
4.1.6. Level of radiated noise	72
4.1.7. Inherent noise	75
4.1.8. Inherent and radiated noises	78
Chapter 5. Transmission of the Acoustic Signal: Sonar Equations	79
5.1. Introduction	79
5.2. Detection contrast and detection index	80
5.3. Transmission equation	81
5.4. Equation of passive sonar	88
5.5. Equation of active sonar	89
PART 2. ACOUSTIC-ELECTRIC INTERFACE ANTENNA STRUCTURES	93
Part 2. Introduction	95
Chapter 6. Electric-acoustic and Acoustic-electric Transformations	97
6.1. Transducers and hydrophones	97
6.1.1. General points	97
6.1.2. Magnetostriction	97
6.1.3. Electrostriction	102
6.1.4. Piezoelectricity	103
6.1.5. Electromagnetism	105
6.1.6. Optics	106
6.1.7. The responses of transducers and hydrophones	106
Chapter 7. Performance and Structures of Acoustic Antennas	113
7.1. Antennas and radiation	113
7.1.1. Equations governing propagation	113
7.1.2. Plane wave solutions	122
7.1.3. Spherical wave solutions	128
7.1.4. Acoustic sources: wave production	132
7.1.5. Directivity and gain of sources and antennas	144
7.1.6. Radiation impedance	185
7.2. Structures of sources and antennas	189
7.2.1. Sources and sensors	189
7.2.2. Antenna structures	200

Chapter 8. Electronic Transducer-hydrophone Adaptation	211
8.1. Hydrophones	211
8.1.1. Simplified equivalent electric diagram of a hydrophone.	212
8.1.2. Association of a hydrophone and an amplifier	215
8.1.3. Noise sources of a hydrophone	227
8.1.4. Noise characterization of a hydrophone-amplifier assembly.	231
8.1.5. Hydrophone association	239
8.2. Transducers	243
8.2.1. Equivalent diagram of a transducer	244
8.2.2. Input immittance.	251
8.2.3. Transfer function of the transducer	254
8.2.4. Adaption circuit at the emitter	261
Chapter 9. Electro-mechano-acoustic Analogies	269
9.1. Methods of studying transducers and hydrophones.	269
9.2. Mechanic-electric equivalence	270
9.2.1. Properties of the two equivalences	271
9.2.2. Electric-mechanic relationships.	273
9.3. Electric-acoustic equivalence	275
9.3.1. Acoustic \Leftrightarrow mechanic connection	278
9.3.2. Acoustic \Leftrightarrow electric matching	281
9.3.3. Equivalent diagram of a piezoelectric ceramic.	304
9.4. Finite element method (FEM)	320
PART 3. PROCESSING CHAIN OF ACTIVE SONAR	323
Part 3. Introduction	325
Chapter 10. Selection Criteria in Active Processing	327
10.1. Selection criteria related to propagation.	327
10.1.1. Dipping sonar.	330
10.1.2. Towed sonar	330
10.2. Selection criteria relative to noise	331
10.3. Selection criteria related to reverberation.	332
10.4. Selection criteria related to emission power	333
10.5. Selection criteria related to the antenna	335
10.6. Selection criteria for the operating frequency	336
10.7. Selection criteria related to operational considerations.	337
10.8. Selection criteria related to the nature of targets	337
Chapter 11. Processing Chain in Active Sonar	341
11.1. General points	341
11.2. Emission	341
11.2.1. The pilot generator	342
11.2.2. Delay control	342
11.2.3. The power amplifier	343
11.2.4. Emission reception switching	344
11.3. Reception.	345
11.3.1. Input conditioning	346
11.3.2. Gain control AGC-TVG	365
11.3.3. Beamforming	383
11.3.4. Adapted processing	406
11.3.5. Information processing of sonar channels.	427
11.3.6. Channel stabilization	435
11.3.7. Audiofrequency channels.	449

Chapter 12. Basic Theoretical Notions in Active Processing	459
12.1. The Doppler effect	459
12.1.1. Definition of the Doppler effect	459
12.1.2. Typical cases of the Doppler effect	461
12.2. The Doppler effect in active sonar conditions	464
12.2.1. Doppler effect on the signal	464
12.2.2. Doppler effect on reverberation	466
12.2.3. Reverberation on a sonar reception channel	468
12.3. Treatment of the signal	485
12.3.1. Detection	485
12.3.2. Estimation	493
12.3.3. Detection performances	497
12.4. Choice of an emission signal under active sonar conditions	503
12.4.1. The active sonar problem	503
12.4.2. The ambiguity function	504
12.4.3. Ambiguity functions of useful signals	509
Chapter 13. Measurement in Underwater Acoustics	525
13.1. Introduction	525
13.1.1. Background	525
13.1.2. Far-field conditions	526
13.2. Wave train method	531
13.2.1. Determination of measuring parameters	531
13.2.2. Limitations of the wave train method	533
13.3. Precautions before measuring	539
13.3.1. Preparation and set up of transducers within the tank	539
13.3.2. Identification and treatment of disruptive noises	540
13.4. Acoustic measurements and calibrations of transducers	542
13.4.1. Measurements of the sensitivities of the transmitter and receiver	543
13.4.2. Comparison calibration method	544
13.4.3. Reciprocity calibration methods	546
13.5. Notion of uncertainty estimation and of maximum tolerated difference	551
13.6. Other types of measurements in underwater acoustics	553
13.6.1. Regular/usual measurement types	553
13.6.2. Unusual/specific measurement types	553
13.6.3. Conclusion	554
APPENDICES	555
Appendix 1. Logarithmic Scales	557
Appendix 2. Equation of Sound in Fluids	563
Appendix 3. Piezoelectricity Fundamentals	571
Appendix 4. Vector Analysis – Fundamentals	579
Appendix 5. Reciprocity Theorem	593
Appendix 6. Concrete Example of Uncertainty Estimation Based on the Reciprocity Calibration Method	601
Bibliography	619
Index	623