

Table of Contents

Preface	ix
Chapter 1. Vibration Theory	1
1.1. Problem	1
1.1.1. Justification of tests in a mechanical environment	1
1.1.2. Quality of environmental tests	2
1.1.3. Generating sets of vibrations	2
1.1.4. "Shock and vibration" terminology	3
1.1.5. Testing methods	3
1.1.6. Uncertainty in measurement	3
1.1.7. Interlaboratory comparison and proficiency testing	4
1.1.8. Metrology management	4
1.2. Different types of mechanical signals	4
1.2.1. Overview	4
1.2.2. Mathematical prerequisites	5
1.2.3. Types of mechanical signals	13
1.2.4. The different types of mechanical signals – a practical approach	17
1.3. Theory of vibration – reminders	19
1.3.1. Fundamental law of dynamics	19
1.3.2. Concept of DOF	19
1.3.3. Systems comprising 1 DOF	20
1.3.4. Free oscillations of an undamped system	22
1.3.5. Free oscillations from an undamped system	23
1.3.6. Forced oscillations of a damped system	27
1.3.7. Systems with several coupled DOF	36
1.4. Concept of mechanical impedance	46
1.4.1. Overview	46
1.4.2. Definitions	47
1.4.3. Resonance and antiresonance	60
1.4.4. Problems with environmental laboratory simulation	66
1.4.5. Conclusion	68
1.5. Electromechanical analogies	68
1.5.1. Overview	68
1.5.2. Maxwell's analogy of the "force tension" type	70
1.5.3. Darrieus' Analogy "force intensity"	71
1.5.4. Units and electrical mechanical correspondence	74
1.5.5. Establishment of electric diagrams	75
1.6. Analog and logic computer simulation	78
1.6.1. Overview	78
1.6.2. Structure of an analog and logic calculator	78

1.6.3. Resolution of various systems	78
1.6.4. Sequential programming of analog computers	79
1.7. Conclusion	80
Chapter 2. Signal Analysis.	81
2.1. Overview	81
2.1.1. Temporal or spectral form	81
2.1.2. Correlation functions	81
2.1.3. Probabilities	82
2.1.4. Spectral analysis	82
2.1.5. Notion of shock spectrum	84
2.2. Spectral density of power.	85
2.2.1. Overview.	85
2.2.2. PSD Study.	87
2.3. FS–Fourier Integral	103
2.3.1. Overview.	103
2.3.2. Considerations of use.	105
2.3.3. Analysis of the results.	105
2.3.4. Calculation example.	106
Chapter 3. Test Preparation.	109
3.1. Test demand analysis and associated test specifications	109
3.1.1. Review of testing demand	109
3.1.2. Test specifications analysis	110
3.1.3. Commercial proposal or contract.	111
3.1.4. Order review	111
3.2. Test initiation	111
3.3. Test fixtures	112
3.3.1. Overview.	112
3.3.2. Principles of construction	114
3.3.3. Concepts of strenght of materials	118
3.3.4. Manufacturing influence	123
3.3.5. Conclusion.	124
3.4. Test execution.	125
3.5. Test reporting	126
Chapter 4. Testing	129
4.1. Sine vibration tests	129
4.1.1. Fixed frequency testing	129
4.1.2. Swept sine tests	130
4.1.3. Conclusion.	146
4.2. Vibration testing in noise or random	146
4.2.1. Overview.	146
4.2.2. Concepts on random functions	148
4.2.3. Random vibrations.	153
4.3. Specific tests	158
Chapter 5. Equipment Applications.	163
5.1. Vibration sources and effects	163
5.1.1. Overview.	163
5.1.2. Vibration sources	163

5.1.3. Vibration effects	164
5.1.4. Notions of fatigue and damage due to vibrations	164
5.2. Electronic equipment	167
5.2.1. In land vehicles	167
5.2.2. In ships and submarines	168
5.2.3. In aircrafts, helicopters, missiles	169
5.2.4. Conclusion	170
5.3. Design of electronic equipment subjected to vibrations	170
5.3.1. Operating mode	170
5.3.2. Design techniques	172
5.3.3. Printed circuit boards	177
5.3.4. Components assembly	183
5.3.5. Cases	185
5.3.6. Wiring	190
5.3.7. Conclusion	191
5.4. Study of a particular case – example of analysis of an electronic bay	191
Chapter 6. Controlling Generators of Vibrations and Shocks	197
6.1. General principles	197
6.2. Typical configuration of the equipment used	199
6.3. Traceability of tests	199
6.4. Control in sinusoidal mode	200
6.4.1. Generalities	200
6.4.2. Generating a signal	201
6.4.3. Signal acquisition	201
6.4.4. Measurements	201
6.4.5. Corrections	204
6.4.6. Safety devices on controllers	205
6.4.7. Safety devices on the measuring channels	205
6.4.8. Back-ups	206
6.4.9. Deferred time	206
6.5. Random control	207
6.5.1. Signal generation	207
6.5.2. Acquisition of measurements	213
6.6. Shock and transient control	215
6.6.1. Generation in temporal form	215
6.6.2. Generation and control in the shock spectrum	219
6.7. Combined vibrations control	223
6.7.1. Overview	223
6.7.2. Methods	224
6.7.3. Current and emerging needs	225
6.8. Control: a few essential rules	227
Chapter 7. Metrology of Measurement and Testing Methods	229
7.1. Introduction to accelerometer sensors	229
7.1.1. Overview	229
7.1.2. Principle of operation	230
7.1.3. Main features	232
7.1.4. Calibration of accelerometer sensors	236
7.1.5. Accuracy of accelerometers	238
7.1.6. Sensor installation rules	238

7.2. Measurement amplifiers	239
7.2.1. Overview	239
7.2.2. Equivalent circuit	239
7.2.3. Voltage amplifier	240
7.2.4. Charge converters	241
7.3. Validation and verification of the testing means	245
7.4. Control of metrology in a testing laboratory	246
Chapter 8. Testing Means for Vibrations	253
8.1. Electrodynamic exciters	253
8.1.1. Brief description of an electrodynamic exciter	253
8.1.2. Impact opportunities and performance	255
8.1.3. Producing an acceleration pulse on the movable table of a shaker	256
8.1.4. Modeling an electrodynamic exciter	261
8.1.5. Evaluation of the modeling parameters	273
8.2. Hydraulic exciters	281
8.2.1. Overview	281
8.2.2. Principle of operation	281
8.2.3. Hydraulic operation equations	283
8.2.4. Use in impact tests	293
8.2.5. Conclusion	295
Conclusion	297
Appendices	299
Appendix A. Fundamental Laws of Hydraulics – Application to the Study of Hydraulic Vibration Generators	301
Appendix B. Study of the Basic Model with Damping	315
Appendix C. Natural Frequencies of 1,6 mm Thick Cards Equipped with Stiffeners	319
Appendix D. Resonance Frequencies of IC Cards Depending on the Mounting Conditions	323
Appendix E. Concept of Cepstrum	327
Appendix F. Tolerances on Vibration Fixtures	329
Appendix G. Determining Measurement Uncertainty – Example of a Calibration Method for Accelerometer Sensors	331
Appendix H. Example of MPE Allowances	361
Appendix I. List of Testing Methods in Standard Environments	367
Appendix J. Control Strategies – Simplified Summary	379
Appendix K. Mathematical Elements Involved in the Estimation of Uncertainties (Supplementary)	385
Bibliography	403
Index	407