
Contents

Preface	ix
List of Acronyms and Notations	xi
Chapter 1. Introduction – Models and Dynamic Systems	1
1.1. Overview	1
1.2. Industrial process modeling	3
1.3. Model classes.	5
1.3.1. State space models	5
1.3.2. Input–output models	12
Chapter 2. Linear Identification of Closed-Loop Systems	21
2.1. Overview of system identification	21
2.2. Framework	22
2.3. Preliminary identification of a CL process	27
2.3.1. Multivariable linear identification methods	27
2.3.2. Estimation of linear MIMO models using the LSM.	30
2.3.3. Identifying CL processes using the MV-LSM	35
2.4. CLOE class of identification methods	39
2.4.1. Principle of CLOE methods.	39
2.4.2. Basic CLOE method	41
2.4.3. Weighted CLOE method	46
2.4.4. Filtered CLOE method or adaptively filtered CLOE	56
2.4.5. Extended CLOE method.	58
2.4.6. Generalized CLOE method	65

2.4.7. CLOE methods for systems with integrator	74
2.4.8. On the validation of CLOE identified models	78
2.5. Application: identification of active suspension	80
Chapter 3. Digital Control Design Using Pole Placement	93
3.1. Digital proportional-integral-derivative algorithm control	93
3.2. Digital polynomial RST control	96
3.3. RST control by pole placement	98
3.3.1. RST control for regulation dynamics	99
3.3.2. RST polynomial control for tracking dynamics (setpoint change)	100
3.3.3. RST control with independent objectives in tracking and regulation	101
3.4. Predictive RST control	104
3.4.1. Finite horizon predictive control	105
3.4.2. Predictive control with unitary horizon	107
Chapter 4. Adaptive Control and Robust Control	113
4.1. Adaptive polynomial control systems	113
4.1.1. Estimation of the parameters for closed-loop systems	114
4.1.2. Design of the adaptive control	115
4.2. Robust polynomial control systems	117
4.2.1. Robustness of closed-loop systems	118
4.2.2. Studying the stability–robustness connection	121
4.2.3. Study of the nonlinearity–robustness connection	123
4.2.4. Study of the performance–robustness connection	124
4.2.5. Analysis of robustness in the study of the sensitivity function	125
4.2.6. Design of the robust RST control	127
4.2.7. Calibrating the sensitivity function	128
Chapter 5. Multimodel Control	131
5.1. Construction of multimodels	132
5.1.1. Fuzzy logic: Mamdani models	132
5.1.2. Identification from input–output data: direct method	138
5.1.3. Identification from input–output data: neural approach	139
5.1.4. Linearization around various operating points	141
5.1.5. Convex polytopic transformation from an analytical model refined for the command	141
5.1.6. Calculation of the validity of base models	143

5.2. Stabilization and control of multimodels	144
5.3. Design of multimodel command: fuzzy approach	144
5.4. Trajectory tracking	145
Chapter 6. III-Defined and/or Uncertain Systems	147
6.1. Study of the stability of nonlinear systems from vector norms	147
6.1.1. Vector norms	147
6.1.2. Comparison systems and overvaluing systems	148
6.1.3. Determination of attractors	153
6.1.4. Nested attractors [GHA 15a]	156
6.2. Adaptation of control	156
6.2.1. Minimizing the size of attractors: direct approach	156
6.2.2. Minimizing the size of attractors by metaheuristics	157
6.3. Overvaluation of the maximum error for various applications	157
6.3.1. Control of nonlinear systems by pole placement	157
6.3.2. Diffeomorphism command of nonlinear processes	159
6.3.3. Determining the attractor for Lur'e Postnikov type processes [GHA 14]	161
6.3.4. Minimizing the attractor through tabu search	165
6.4. Fuzzy secondary loop control	171
Chapter 7. Modeling and Control of an Elementary Industrial Process	173
7.1. Modeling and control of fluid transfer processes	173
7.1.1. Modeling fluid flow processes	173
7.1.2. Designing flow control systems	178
7.2. Modeling and controlling liquid storage processes	180
7.2.1. Constant output flow	181
7.2.2. Variable output flow	183
7.2.3. Designing liquid level control systems	185
7.3. Modeling and controlling the storage process of a pneumatic capacitor	187
7.3.1. Modeling a pneumatic capacitor	187
7.3.2. Designing pneumatic capacitor control systems	190
7.4. Modeling and controlling heat transfer processes	191
7.4.1. Modeling a thermal transfer process	191
7.4.2. Designing temperature control systems	194
7.5. Modeling and control of component transfer processes	195
7.5.1. Modeling a chemical mixing process without reaction	195

7.5.2. Modeling a chemical reaction process.	198
7.5.3. Designing systems for controlling the concentration of chemical components	200
Chapter 8. Industrial Applications – Case Studies	203
8.1. Digital control for an installation of air heating in a steel plant	203
8.1.1. Automation solution and design of the control algorithms	204
8.1.2. Optimization of the combustion process	207
8.2. Control and optimization of an ethylene installation.	210
8.2.1. Automation solution and designing the control algorithms	211
8.2.2. Optimizing the pyrolysis process.	217
8.3. Digital control of a thermoenergy plant	219
8.3.1. Solving the problem of automation of a thermal operating point	220
8.3.2. Optimization of thermal transfer and agent product.	225
8.4. Extremal control of a photovoltaic installation	226
8.4.1. Extremal control of a photovoltaic panel	237
Appendix A.	243
Appendix B.	249
Appendix C.	257
Appendix D.	261
Bibliography.	271
Index	279